

**ADwin** systems are used by engineers and scientists for data acquisition, automation and Real-Time control applications. **ADwin** always provides a very accurate, precise and deterministic timing, with a high speed process execution.

**ADwin-X** is the newest member of the **ADwin** Real-Time systems family. It is compact and is designed for OEM applications to be used inside machines and devices. Like all **ADwin** systems it executes a fast, robust and flexible Real-Time code.

There are standard versions of **ADwin-X**, as well as fully customized versions for OEM series applications.

**ADwin-X** is free programmable by the user. The software of the system can be designed using the **ADbasic** tool chain or Matlab®/Simulink® and it can be adapted just in software for many kinds of applications and solutions. For the data exchange with a PC, all drivers are available for the **ADwin-X**.

In general, **ADwin** offers more than 25 years of experience in automation and deterministic Real-Time applications. With software solutions since 1987, and with **ADwin** hardware systems since 1992, many thousands of users and applications worldwide rely on these precise and robust systems.

**ADwin** systems are the core of various test stands, machines and scientific experiment controls.



### Application Fields

- Test stand control and data acquisition
- Automotive and Aerospace test stands
- Dynamic component testing
- Material endurance tests
- Fast machine control applications
- Scientific and industrial research
- Production line automation systems
- Laboratory and mobile systems
- EOL – End of Line testing

### Real-Time Functions

- Intelligent data acquisition
- Fast digital closed loop controller
- Multi axis controller, PID and others
- Online analysis of measurement data
- Complex trigger applications
- Online data reduction
- Signal generation, arbitrary, adaptive

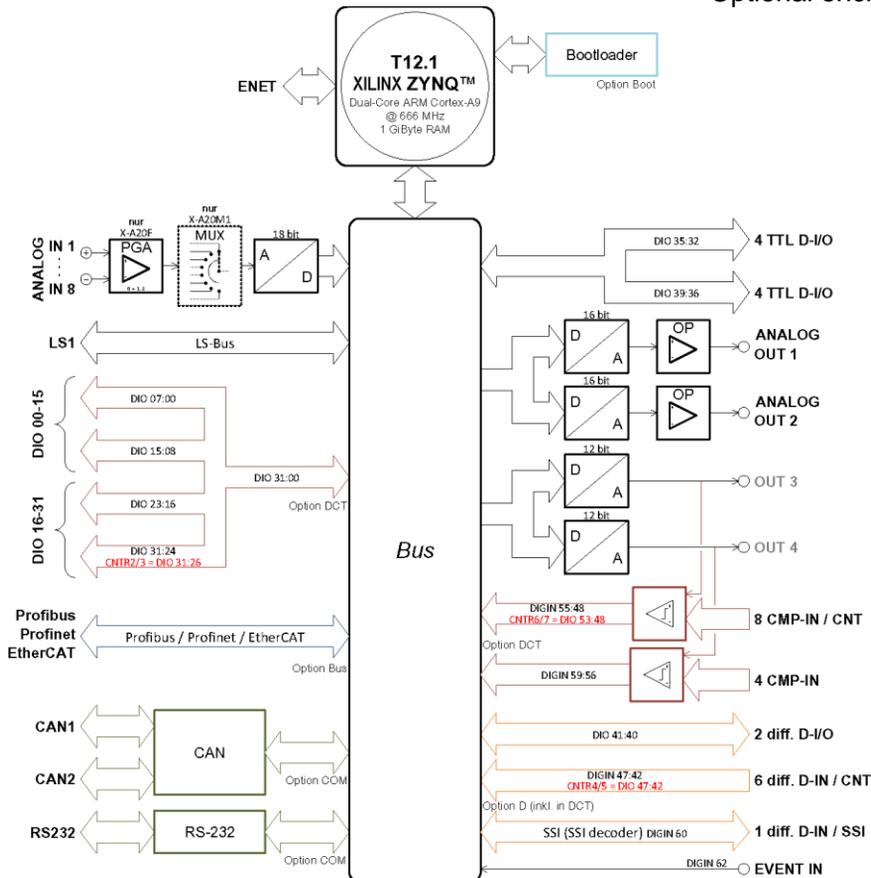
|   |  |                                    |                          |  |
|---|--|------------------------------------|--------------------------|--|
| <p><b>8 analog in</b><br/>18bit, +/-10V, MUX</p> <p>alternatively, optional:<br/><b>8 analog in</b><br/>18bit, +/-10V, Parallel</p> | <p><b>ADwin-X</b></p> <p>CPU T12.1<br/>CPU ZYNQ, ARM Dual<br/>Cortex-A9, 667MHz,<br/>64-bit Floating Point Unit,<br/>1GB RAM,<br/>Fast RT-OS</p> <p>1GBit Ethernet to the PC</p> | <p><b>32 DIO</b><br/>TTL</p>       | <p><b>2 CAN</b></p>      | <p><b>2 Counter</b><br/>TTL, Up/down,<br/>quadrature, PWM, pulse</p>       |
| <p><b>2 analog out</b><br/>16bit, +/-10V <sup>+1)</sup></p>   |  | <p><b>1 RS232</b></p>              | <p><b>1 ETHERCAT</b></p> | <p><b>2 Counter</b><br/>diff TTL, PWM, pulse,<br/>Up/down, quadrature,</p> |
| <p><b>4+4 TTL DIO</b><br/><b>1 EVENT In</b></p>   |  | <p><b>7+2 DIO</b><br/>diff TTL</p> | <p><b>1 PROFIBUS</b></p> | <p><b>2 Counter</b><br/>12V/24V, PWM, pulse,<br/>Up/down, quadrature</p>   |
| <p>Standard</p>   |  | <p><b>Bootloader</b></p>           | <p><b>1 PROFINET</b></p> | <p><b>32+ DIO 24V</b><br/>Up to 15x32 channel<br/>24V I/O via LS bus</p>   |
|   |  | <p>Optional</p>                    |                          |  |

## Standard version

- CPU: XILINX ZYNQ™ with Dual-Core ARM Cortex-A9, 64-Bit FPU (double precision), 32 Bit Integer, 667 MHz, 1 Gigabyte main memory for program code and measurement data
- Ethernet interface (1000Mbit/sec) for PC communication
- 8 analog inputs 18 Bit, 5  $\mu$ s,  $\pm$ 10V
- 2 analog outputs 16 Bit,  $\pm$ 10V
- 2 outputs comp. threshold 10 Bit, low speed
- 8 TTL digital channels inputs/outputs
- 1 trigger input (Event), pos. TTL logic
- serial LS-bus interface for module [HSM-24V](#)
- Dimensions: 215 × 125 × 47 mm

## Ordering options

- 8 analog inputs wit parallel acquisition @ 5  $\mu$ s for 8 channels
- Counter blocks, each with up/down counter (A/B, clock/dir), PWM counter or puls counter, 32 bit
  - 2 channels TTL
  - 2 channels differential TTL
  - 2 channels comparator inputs
- 1 SSI interface
- 32 TTL digital channels, inputs/outputs
- 8 digital inputs differential
- 2 digital comparator inputs
- 2 CAN interfaces (high speed)
- 1 RS232 interface
- 1 Profibus / Profinet / EtherCAT
- Bootloader for stand-alone operation
- Optional enclosure version for 19" rack



### ADwin-X-A20

|                       |   |
|-----------------------|---|
| <b>ADwin-X-A20-M1</b> | CPU ZYNQ, ARM Dual Cortex-A9, 667MHz, 64Bit FPU, 1GB RAM<br>Ethernet zum PC, 1x Event , 8x TTL-IO, 1x LS-Bus (Gehäuse 215x125x47)<br>8 analoge Eingänge $\pm 10V$ 18Bit ADC (MUX5 $\mu s$ )<br>2 analoge Ausgänge $\pm 10V$ 16Bit DAC (3 $\mu s$ ), Versorgung 10-28V |
|-----------------------|---|

### ADwin-X-A20 Erweiterungen (Bestelloptionen)

|                        |   |
|------------------------|---|
| <b>A20-F</b>           | ADC ZEITSYNCHRON (5 $\mu s$ für 8 analoge Eingänge)   |
| <b>A20-D</b>           | 2x CNT-D Zähler 32Bit V/R, Periode, Takt, 1x SSI (7x RS422, 2x RS485)   |
| <b>A20-DCT</b>         | 2x CNT-D Zähler 32Bit V/R, Periode, Takt, 1x SSI (7x RS422, 2x RS485)<br>32TTL-IO, 2x CNT-T, FIFO 64Bit<br>12x IO 30V/2 $\mu s$ Schaltschwelle 0-5V, 2x CNT-C<br>2x CAN, 1x RS232 |
| <b>A20-COM</b>         |   |
| <b>A20-Profibus-SL</b> | 1x Profibus-DP Slave-Schnittstelle, 9-pol. DSub   |
| <b>A20-EtherCAT-SL</b> | 1x EtherCAT Slave-Schnittstelle, RJ45-Stecker   |
| <b>A20-Boot</b>        | Bootloader zum Betrieb ohne PC  |

### Zubehör

|                      |   |
|----------------------|---|
| <b>A20-Mount</b>     | Hutschienenmontage für das ADwin-A20-System   |
| <b>A20-Pow</b>       | Netzteil, 12V DC Spannungsversorgung für ADwin-A20  |
| <b>A20-Pow-Mount</b> | Netzteil für DIN Montage, 12V DC Spannungsversorgung für ADwin-A20  |
| <b>HSM-24V</b>       | 32 Digital-I/Os, 24V Pegel, in 8er Gruppen konfigurierbar<br>Hutschienenmodul für LS-Bus-Schnittstelle, Schraubklemmanschluss |
| <b>ADbasic</b>       | Schnelles Echtzeit-Entwicklungstool für die ADwin-Systeme, Version 6  |



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